

24-Bit, Stereo D/A Converter for Digital Audio

Features

- 24-Bit Conversion
- 115 dB Signal-to-Noise-Ratio (EIAJ)
- 106 dB Dynamic Range
- -97 dB THD+N
- 128X Oversampling
- Low Clock Jitter Sensitivity
- Filtered Line-Level Outputs
Linear Phase Filtering
Zero Phase Error Between Channels
- Adjustable System Sampling Rates
including 32 kHz, 44.1 kHz & 48 kHz
- Digital De-emphasis for 32 kHz, 44.1 kHz & 48 kHz
- Pin Compatible with CS4329

General Description

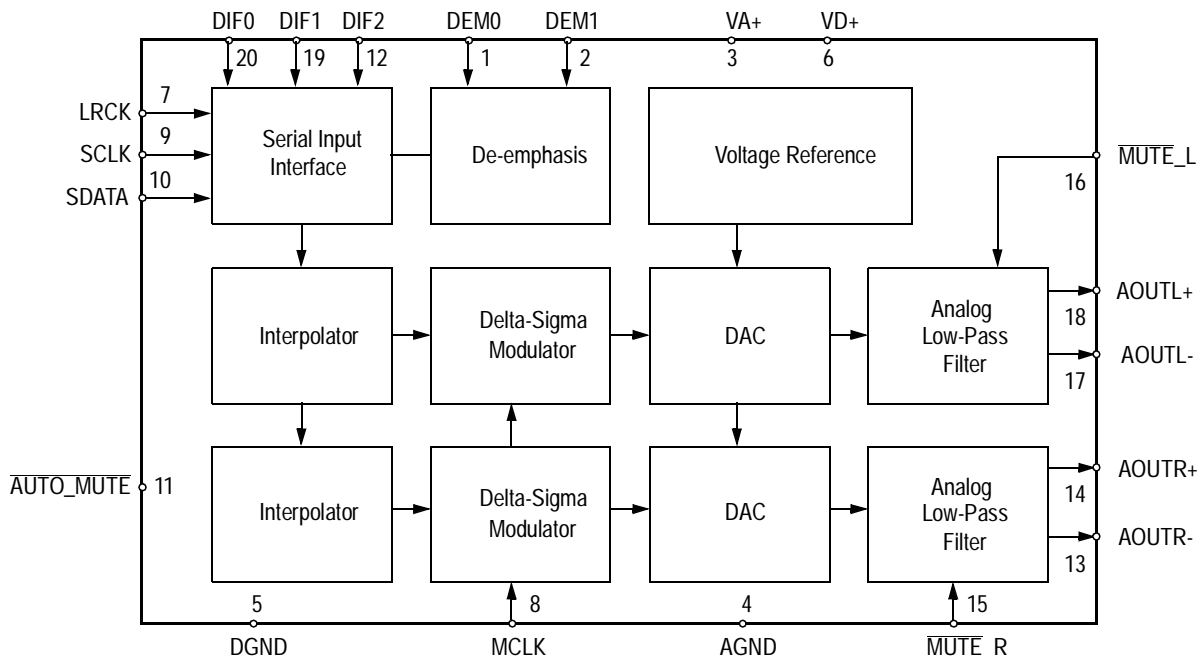
The CS4390 is a complete stereo digital-to-analog output system. In addition to the traditional D/A function, the CS4390 includes a digital interpolation filter followed by 128X oversampled delta-sigma modulator. The modulator output controls the reference voltage input to an ultra-linear analog low-pass filter. This architecture allows for infinite adjustment of sample rate between 1 and 50 kHz while maintaining linear phase response simply by changing the master clock frequency.

The CS4390 also includes an extremely flexible serial port utilizing mode select pins to support multiple interface formats.

The master clock can be either 256, 384, or 512 times the input sample rate, supporting various audio environments.

ORDERING INFORMATION

CS4390-KP	-10 to 70 °C	20-pin Plastic DIP
CS4390-KS	-10 to 70 °C	20-pin Plastic SSOP
CDB4390		Evaluation Board



Preliminary Product Information

This document contains information for a new product. Cirrus Logic reserves the right to modify this product without notice.

ANALOG CHARACTERISTICS ($T_A = 25\text{ }^\circ\text{C}$; Full-Scale Differential Output Sine wave, 997 Hz; $F_s = 48\text{ kHz}$; Input Data = 24 Bits; SCLK = 3.072 MHz; $R_L = 20\text{ k}\Omega$ differential; $V_{D+} = V_{A+} = 5\text{V}$; Logic "1" = V_{D+} , Logic "0" = DGND; Measurement Bandwidth is 10 Hz to 20 kHz; unweighted; unless otherwise specified)

Parameter	Symbol	Min	Typ	Max	Unit
Specified Temperature Operating Range	T_A	-10	-	70	$^\circ\text{C}$
Dynamic Performance					
Dynamic Range	(Note 1)				
24-Bit	(A-Weighted)	98	103	-	dB
20-Bit	(A-Weighted)	101	106	-	dB
16-Bit	(A-Weighted)	-	103	-	dB
	(A-Weighted)	-	106	-	dB
	(A-Weighted)	-	94	-	dB
	(A-Weighted)	-	96	-	dB
Total Harmonic Distortion + Noise	(Note 1)	THD+N			
24-Bit	0 dB	TBD	-97	-	dB
	-20 dB	TBD	-83	-	dB
	-60 dB	TBD	-43	-	dB
20-Bit	0 dB	-	-97	-	dB
	-20 dB	-	-83	-	dB
	-60 dB	-	-43	-	dB
16-Bit	0 dB	-	-93	-	dB
	-20 dB	-	-74	-	dB
	-60 dB	-	-34	-	dB
Idle Channel Noise / Signal-to-Noise-Ratio	(Note 2)	-	115	-	dBFS
Interchannel Isolation (1 kHz)		-	-110	-	dB
Combined Digital and Analog Filter Characteristics					
Frequency Response 10 Hz to 20 kHz	(Note 3)	-	± 0.1	-	dB
Deviation from linear phase		-	± 0.5	-	deg
Passband: to -0.1 dB corner	(Note 3)	0	-	21.77	kHz
Passband Ripple		-	-	± 0.001	dB
StopBand	(Note 3)	26.23	-	-	kHz
StopBand Attenuation	(Note 3)	72	-	-	dB
Group Delay		-	$25/F_s$	-	s
De-emphasis Error		-	-	± 0.3	dB
dc Accuracy					
Interchannel Gain Mismatch		-	0.1	-	dB
Gain Error		-	± 2	± 5	%
Gain Drift		-	200	-	ppm/ $^\circ\text{C}$

- Notes:
1. Triangular PDF Dithered Data
 2. $\overline{\text{AUTO-MUTE}}$ active. See parameter definitions
 3. The passband and stopband edges scale with frequency. For input sample rates, F_s , other than 48 kHz, the passband edge is $0.4535 \times F_s$ and the stopband edge is $0.5465 \times F_s$.

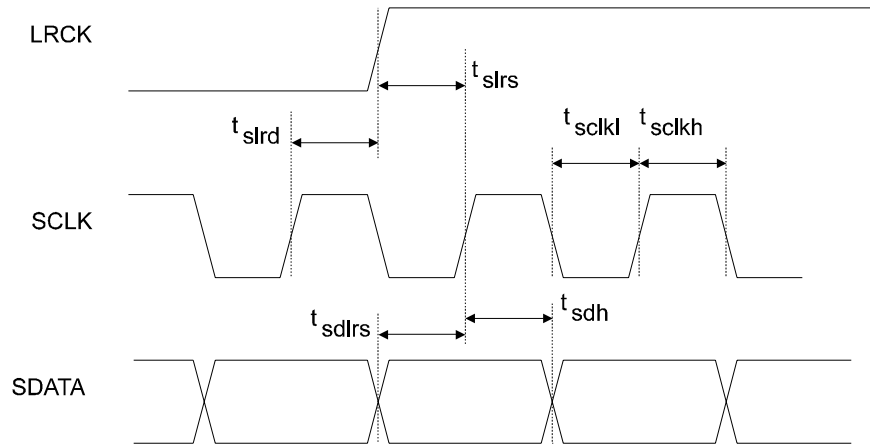
ANALOG CHARACTERISTICS (CONTINUED)

Parameter	Symbol	Min	Typ	Max	Unit	
Power Supplies						
Power Supply Current:	Normal Operation	IA+	-	30	-	mA
		ID+	-	12	-	mA
		(IA+) + (ID+)	-	42	50	mA
	Power-down	(IA+) + (ID+)	-	200	-	μA
Power Dissipation	Normal Operation		-	210	250	mW
	Power-down		-	1	-	mW
Power Supply Rejection Ratio (1 kHz)	PSRR	-	60	-	dB	
Analog Output						
Differential Full Scale Output Voltage	(Note 4)	1.90	2.0	2.10	V _{rms}	
Output Common Mode Voltage		-	2.2	-	V	
Differential Offset		-	3	12	mV	
Load Resistance		TBD	10	-	kΩ	
Load Capacitance		-	-	100	pF	

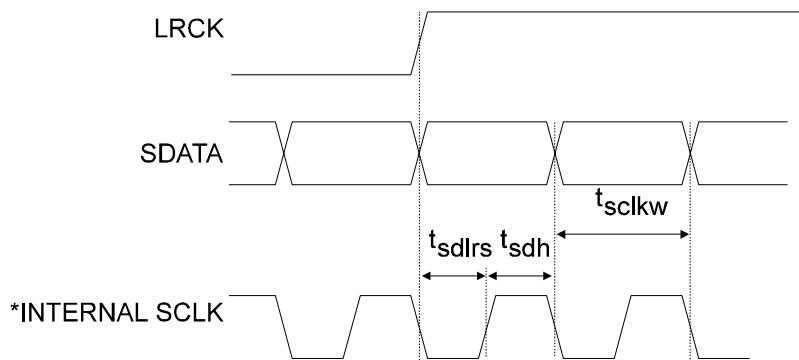
Notes: 4. Specified for a fully differential output $\pm((AOUT+) - (AOUT-))$. See Figure 12.

SWITCHING CHARACTERISTICS ($T_A = 25^\circ\text{C}$; $V_{A+}, V_{D+} = 5.0\text{V}$; Inputs: Logic 0 = 0V, Logic 1 = V_{D+} , $C_L = 20\text{pF}$)

Parameter	Symbol	Min	Typ	Max	Unit
Input Sample Rate	F_s	1	-	50	kHz
MCLK Pulse Width High MCLK / LRCK = 512		10	-	-	ns
MCLK Pulse Width Low MCLK / LRCK = 512		10	-	-	ns
MCLK Pulse Width High MCLK / LRCK = 384		21	-	-	ns
MCLK Pulse Width Low MCLK / LRCK = 384		21	-	-	ns
MCLK Pulse Width High MCLK / LRCK = 256		31	-	-	ns
MCLK Pulse Width Low MCLK / LRCK = 256		31	-	-	ns
External SCLK Mode					
SCLK Pulse Width Low	t_{sckl}	20	-	-	ns
SCLK Pulse Width High	t_{sckh}	20	-	-	ns
SCLK Period	t_{sckw}	$\frac{1}{128(F_s)}$	-	-	ns
SCLK rising to LRCK edge delay	t_{slrd}	20	-	-	ns
SCLK rising to LRCK edge setup time	t_{slrs}	20	-	-	ns
SDATA valid to SCLK rising setup time	t_{sdls}	20	-	-	ns
SCLK rising to SDATA hold time	t_{sdh}	20	-	-	ns
Internal SCLK Mode					
SCLK Period SCLK / LRCK = 64	t_{sckw}	$\frac{1}{64(F_s)}$	-	-	ns
SDATA valid to SCLK rising setup time	t_{sdls}	$\frac{1}{512(F_s)} + 10$	-	-	ns
SCLK rising to SDATA hold time MCLK / LRCK=256 or 512	t_{sdh}	$\frac{1}{512(F_s)} + 15$	-	-	ns
SCLK rising to SDATA hold time MCLK / LRCK = 384	t_{sdh}	$\frac{1}{384(F_s)} + 15$	-	-	ns



External Serial Mode Input Timing



Internal Serial Mode Input Timing

* The SCLK pin must be terminated to ground.
The SCLK pulses shown are internal to the CS4390.

DIGITAL CHARACTERISTICS ($T_A = 25\text{ }^\circ\text{C}$; $V_{D+} = 5V \pm 5\%$)

Parameter	Symbol	Min	Typ	Max	Unit
High-Level Input Voltage	V_{IH}	2.4	-	-	V
Low-Level Input Voltage	V_{IL}	-	-	0.8	V
Input Leakage Current	V_{in}	-	-	± 10.0	μA
Digital Input Capacitance		-	10	-	pF

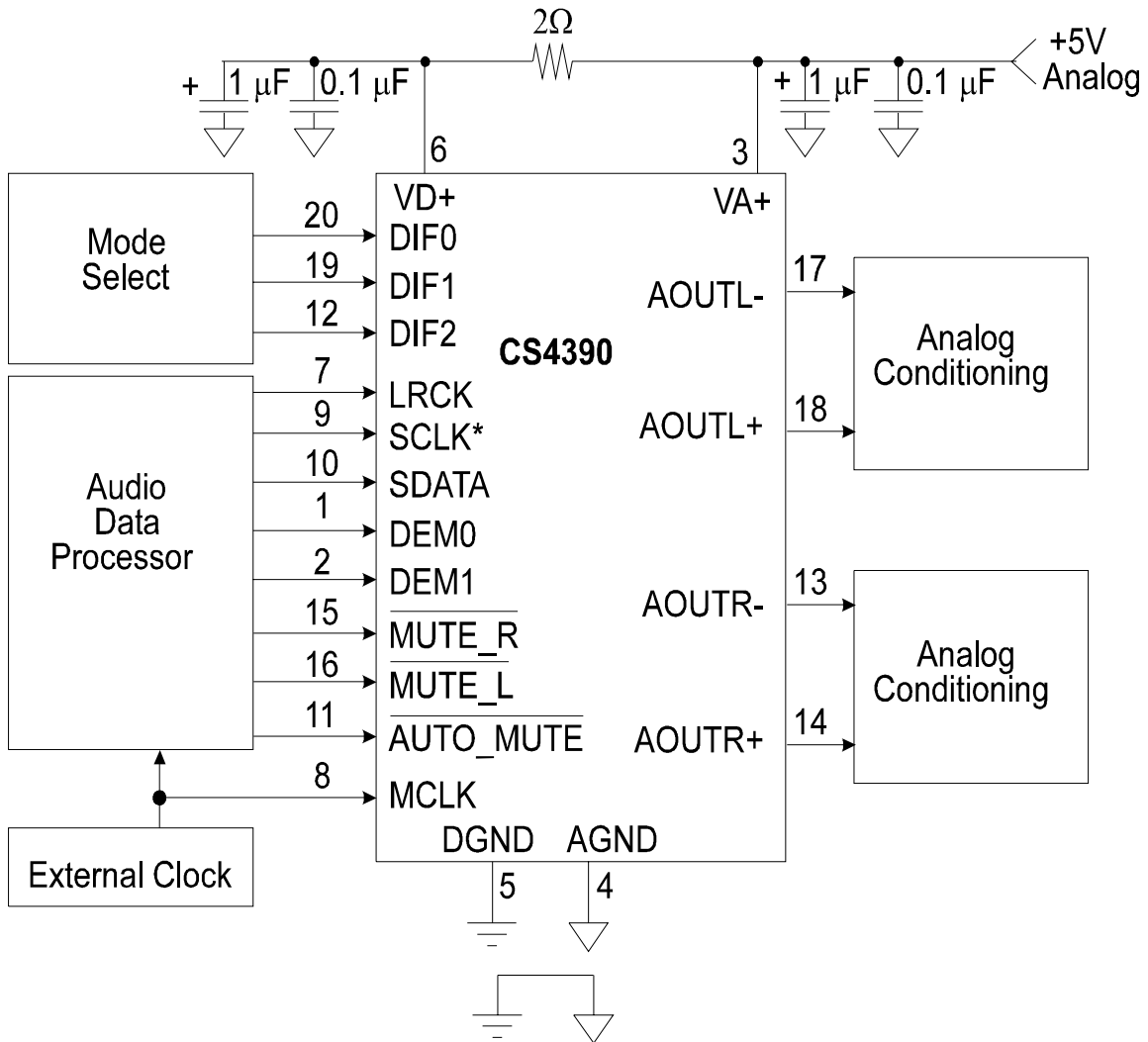
ABSOLUTE MAXIMUM RATINGS (AGND = 0V, all voltages with respect to ground.)

Parameter	Symbol	Min	Max	Unit	
DC Power Supply:	Positive Analog	VA+	-0.3	6.0	V
	Positive Digital	VD+	-0.3	6.0	V
	$ VA+ - VD+ $		0.0	0.4	V
Input Current, Any Pin Except Supplies	I_{in}	-	± 10	mA	
Digital Input Voltage	V_{IND}	-0.3	$(VD+)+0.4$	V	
Ambient Operating Temperature (power applied)	T_A	-55	125	$^\circ\text{C}$	
Storage Temperature	T_{stg}	-65	150	$^\circ\text{C}$	

WARNING: Operation at or beyond these limits may result in permanent damage to the device.
Normal operation is not guaranteed at these extremes.

RECOMMENDED OPERATING CONDITIONS (DGND = 0V; all voltages with respect to ground)

Parameter	Symbol	Min	Typ	Max	Unit	
DC Power Supply:	Positive Digital	VD+	4.75	5.0	5.25	V
	Positive Analog	VA+	4.75	5.0	5.25	V
	$ VA+ - VD+ $		-	-	0.4	V



*SCLK must be connected to DGND for operation in Internal SCLK Mode

Figure 1. Typical Connection Diagram

GENERAL DESCRIPTION

The CS4390 is a complete stereo digital-to-analog system including $128\times$ digital interpolation, fourth-order delta-sigma digital-to-analog conversion, $128\times$ oversampled one-bit delta-sigma modulator and analog filtering. This architecture provides a low sensitivity to clock jitter. The DAC converts digital data at any input sample rate between 1 and 50 kHz, including the standard audio rates of 48, 44.1 and 32 kHz.

The primary purpose of using delta-sigma modulation techniques is to avoid the limitations of laser trimmed resistive DAC architectures by using an inherently linear 1-bit DAC. The advantages of a 1-bit DAC include: ideal differential linearity, no distortion mechanisms due to resistor matching errors and no linearity drift over time and temperature due to variations in resistor values.

Digital Interpolation Filter

The digital interpolation filter increases the sample rate by a factor of 4 and is followed by a $32\times$ digital sample-and hold to effectively achieve a $128\times$ interpolation filter. This filter eliminates images of the baseband audio signal which exist at multiples of the input sample rate, F_s . This allows for the selection of a less complex analog filter based on out-of-band noise attenuation requirements rather than anti-image filtering. Following the interpolation filter, the resulting frequency spectrum has images of the input signal at multiples of $128\times$ the input

sample rate. These images are removed by the external analog filter.

Delta-Sigma Modulator

The interpolation filter is followed by a fourth-order delta-sigma modulator which converts the interpolation filter output into 1-bit data at $128\times F_s$.

Switched-Capacitor DAC

The delta-sigma modulator is followed by a digital-to-analog converter which translates the 1-bit data into a series of charge packets. The magnitude of the charge in each packet is determined by sampling of a voltage reference onto a switched capacitor, where the polarity of each packet is controlled by the 1-bit signal. This technique greatly reduces the sensitivity to clock jitter and is a major improvement over earlier generations of 1-bit digital-to-analog converters where the magnitude of charge in the D-to-A process is determined by switching a current reference for a period of time defined by the master clock.

The CS4390 incorporates a differential output to maximize the output level and to minimize the amount of gain required in the output analog stage. The differential output also allows for the cancellation of common mode errors in the differential to singled-ended converter.

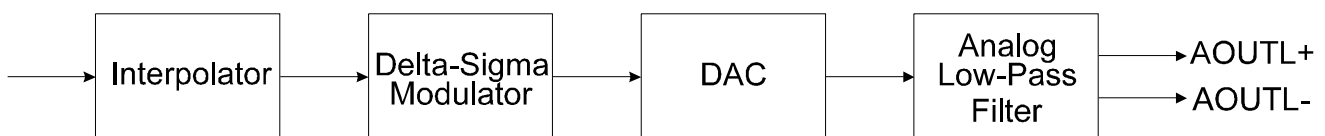


Figure 2. Block Diagram

SYSTEM DESIGN

Master Clock

The Master Clock, MCLK, is used to operate the digital interpolation filter and the delta-sigma modulator. MCLK must be either 256x, 384x or 512x the desired Input Sample Rate, Fs. Fs is the frequency at which digital audio samples for each channel are input to the DAC and is equal to the LRCK frequency. The MCLK to LRCK frequency ratio is detected automatically during the initialization sequence by counting the number of MCLK transitions during a single LRCK period. Internal dividers are then set to generate the proper clocks for the digital filter, delta-sigma modulator and switched-capacitor filter. Table 1 illustrates the standard audio sample rates and the required MCLK frequencies. Once the MCLK to LRCK frequency ratio has been detected, the phase and frequency relationship between the two clocks must remain fixed. If during any LRCK this relationship is changed, the CS4390 will reset.

Fs (kHz)	MCLK (MHz)		
	256x	384x	512x
32	8.1920	12.2880	16.3840
44.1	11.2896	16.9344	22.5792
48	12.2880	18.4320	24.5760

Table 1. Common Clock Frequencies

Serial Data Interface

The Serial Data interface is accomplished via the serial data input, SDATA, serial data clock, SCLK, and the left/right clock, LRCK. The CS4390 supports seven serial data formats which are selected via the digital input format pins DIF0, DIF1 and DIF2. The different formats control the relationship of LRCK to the serial data and the edge of SCLK used to latch the data into the input buffer. Table 2 lists the seven formats, along with the associated figure number. The serial data is represented in 2's-complement format with the MSB-first in all seven formats.

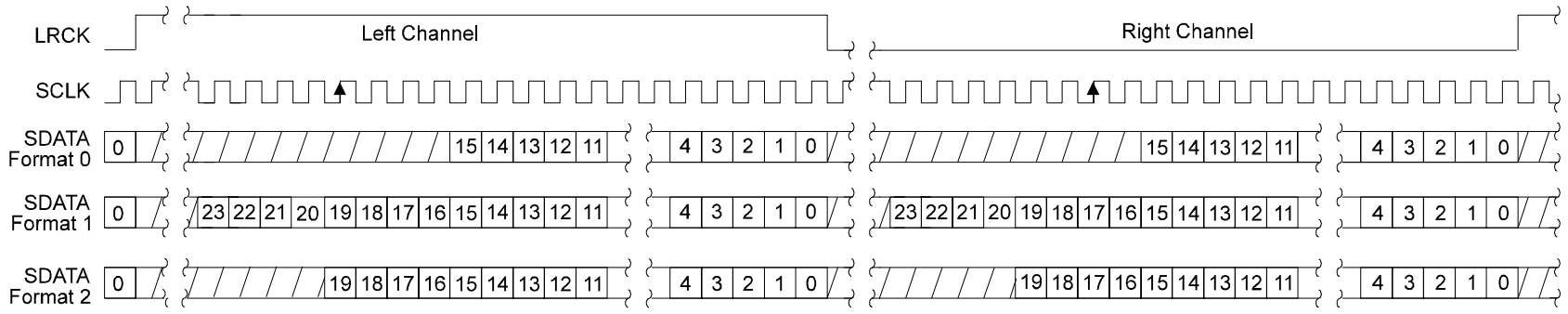
DIF2	DIF1	DIF0	Format	Figure
0	0	0	0	3
0	0	1	1	3
0	1	0	2	3
0	1	1	3	4
1	0	0	4	5
1	0	1	5	6
1	1	0	6	7
1	1	1	Calibrate	-

Table 2. Digital Input Formats

Formats 0, 1, and 2 are shown in Figure 3. The audio data is right-justified, LSB aligned with the trailing edge of LRCK, and latched into the serial input data buffer on the rising edge of SCLK. Formats 0, 1, and 2 are 16, 24, and 20-bit versions, respectively, and differ only in the number of data bits required. Format 1 in the CS4390 is not compatible with Format 1 in the CS4329.

Formats 3 and 4 are 20-bit left justified, MSB aligned with the leading edge of LRCK, and are identical with the exception of the SCLK edge used to latch data. Data is latched on the falling edge of SCLK in Format 3 and the rising edge of SCLK in Format 4. Both formats will support 16, 18, and 20-bit inputs if the data is followed by 8, 6, or 4 zeros to simulate a 24-bit input as shown in Figures 4 and 5. A very small offset will result if the 20, 18, or 16-bit data is followed by static non-zero data.

Formats 5 and 6 are compatible with the I²S serial data protocol and are shown in Figures 6 and 7. Notice that the MSB is delayed 1 period of SCLK following the leading edge of LRCK and LRCK is inverted compared to the previous formats. Data is latched on the rising edge of SCLK. Format 5 is 16-bit I²S while Format 6 is 24-bit I²S. 20, 18, or 16-bit I²S can be implemented in Format 6 if the data is followed by 4, 6, or 8 zeros respectively to simulate a 24-bit input as shown in Figure 7. A very small offset will result if the 20, 18, or 16-bit data is followed by static non-zero data.



NOTE: Format 1 is not compatible with the CS4329.

Figure 3. Digital Input Format 0, 1 and 2.

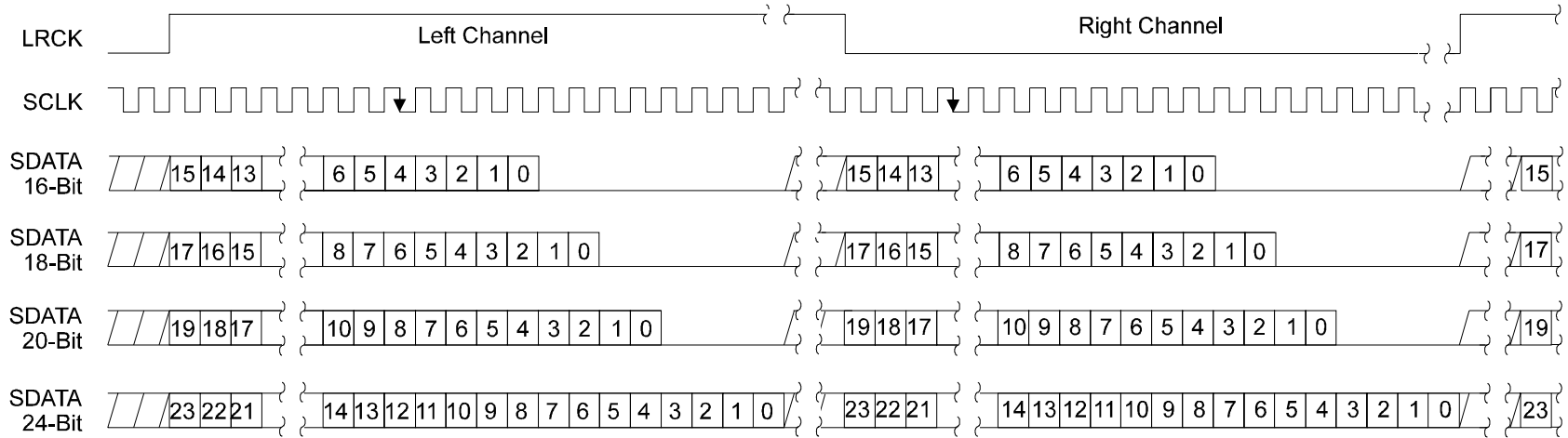


Figure 4. Digital Input Format 3.

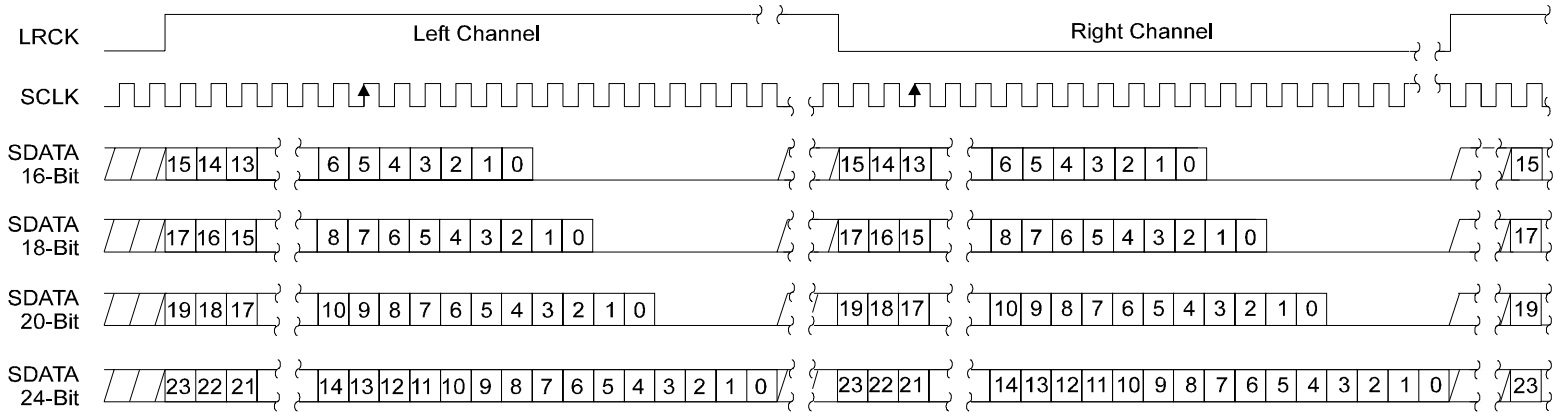


Figure 5. Digital Input Format 4.

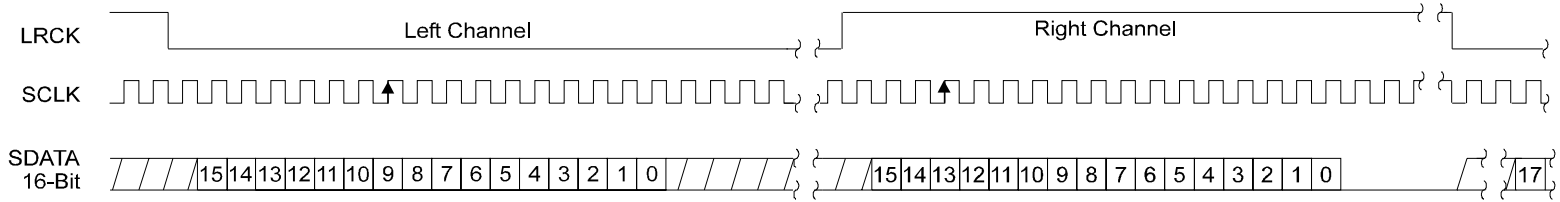


Figure 6. Digital Input Format 5.

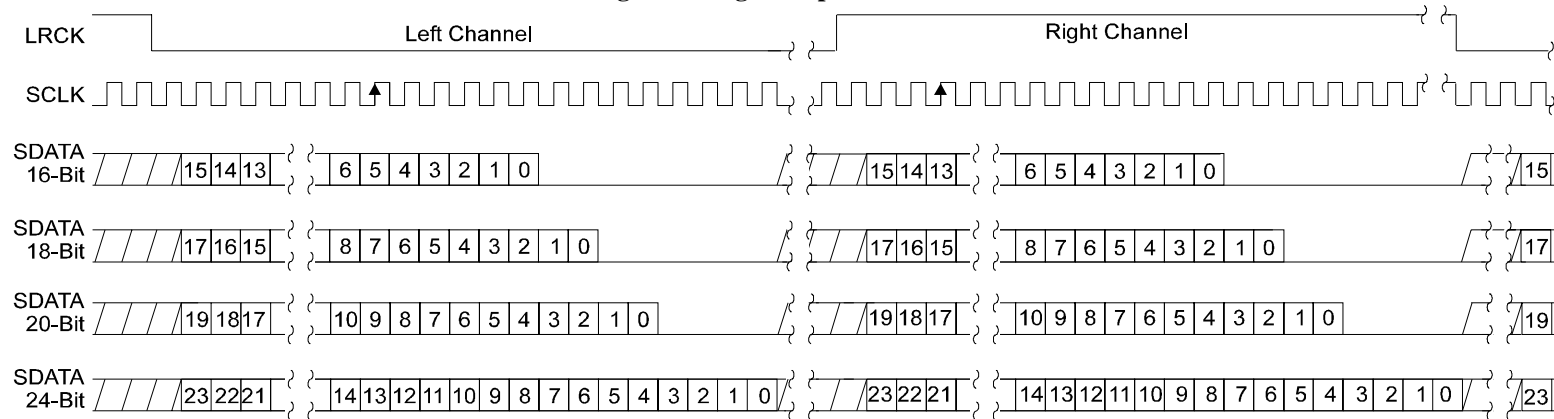


Figure 7. Digital Input Format 6.

Serial Clock

The serial clock controls the shifting of data into the input data buffers. The CS4390 supports both external and internal serial clock generation modes.

External Serial Clock

The CS4390 will enter the external serial clock mode if 15 or more high\low transitions are detected on the SCLK pin during any phase of the LRCK period. When this mode is enabled, internal serial clock mode cannot be accessed without returning to the power down mode.

Internal Serial Clock

In the Internal Serial Clock Mode, the serial clock is internally derived and synchronous with MCLK. The internal SCLK / LRCK ratio is always 64 and operation in this mode is identical to operation with an external serial clock synchronized with LRCK. The SCLK pin must be connected to DGND for proper operation.

The internal serial clock mode is advantageous in that there are situations where improper serial clock routing on the printed circuit board can degrade system performance. The use of the internal serial clock mode simplifies the routing of the printed circuit board by allowing the serial clock trace to be deleted and avoids possible interference effects.

Mute Functions

The CS4390 includes an auto-mute function which will initiate a mute if 8192 consecutive 0's or 1's are input on both the Left and Right channels. The mute will be released when non-zero input data is applied to the DAC. The auto-mute function is useful for applications, such as compact disk players, where the idle channel noise must be minimized. This feature is active only if the `AUTO_MUTE` pin is low and is independent of the status of `MUTE_L` and `MUTE_R`. Either channel can also be muted instantaneously with the `MUTE_L` or `MUTE_R`.

De-Emphasis

Implementation of digital de-emphasis requires re-configuration of the digital filter to maintain the filter response shown in Figure 8 at multiple sample rates. The CS4390 is capable of digital de-emphasis for 32, 44.1 or 48 kHz sample rates. Table 3 shows the de-emphasis control inputs for DEM 0 and DEM 1.

DEM 1	DEM 0	De-emphasis
0	0	32 kHz
0	1	44.1 kHz
1	0	48 kHz
1	1	OFF

Table 3: De-Emphasis Filter Selection

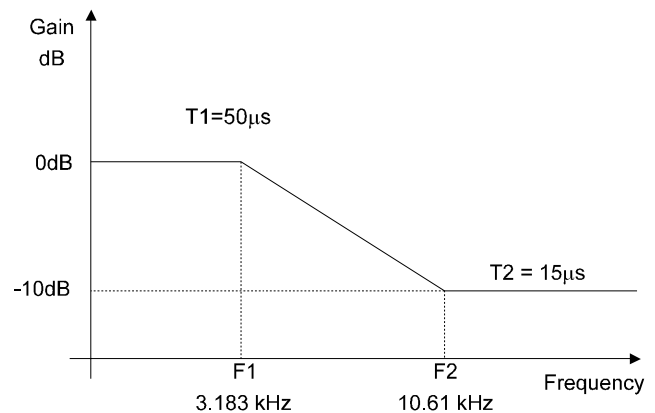


Figure 8. De-emphasis Filter Response

Initialization, Calibration and Power-Down

Upon initial power-up, the DAC enters the power-down mode. The interpolation filters and delta-sigma modulators are reset, and the internal voltage reference, one-bit D/A converters and switched-capacitor low-pass filters are powered down. The device will remain in the power-down mode until MCLK and LRCK are presented. Once MCLK and LRCK are detected, MCLK occurrences are counted over one LRCK period to determine the MCLK / LRCK frequency ratio. The phase and frequency relationship between the two clocks must remain fixed. If during any LRCK this relationship is changed, the CS4390 will reset. Power is applied to

the internal voltage reference, the D/A converters, switched-capacitor filters and the DAC will then enter a calibration mode to properly set the common mode bias voltage and minimize the differential offset. This initialization and calibration sequence requires approximately 2700 cycles of LRCK.

An offset calibration can also be invoked by taking the Format select pins, DIF0, DIF1 and DIF2, to a logic 1 as shown in Table 2. During calibration, the differential outputs are shorted together and the common-mode voltage appears at the output with approximately an 8 kohm output impedance. Following calibration, the analog output impedance becomes less than 10 ohms and the common mode voltage will move to approximately 2.2V .

The CS4390 will enter the power-down mode, within 1 period of LRCK, if either MCLK or LRCK is removed. The initialization sequence, as described above, occurs when MCLK and LRCK are restored.

Combined Digital and Analog Filter Response

The frequency response of the combined analog switched-capacitor and digital filters is shown in Figures 9, 10, and 11. The overall response is clock dependent and will scale with F_s . Note that the response plots have been normalized to F_s and can be de-normalized by multiplying the X-axis scale by F_s , such as 48 kHz.

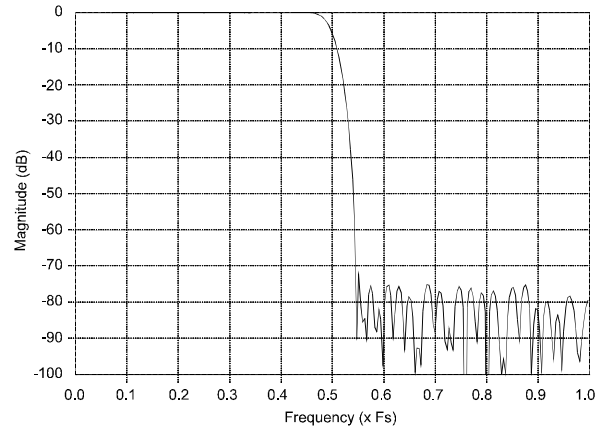


Figure 9. CS4390 Combined Digital and Analog Filter Stopband Rejection

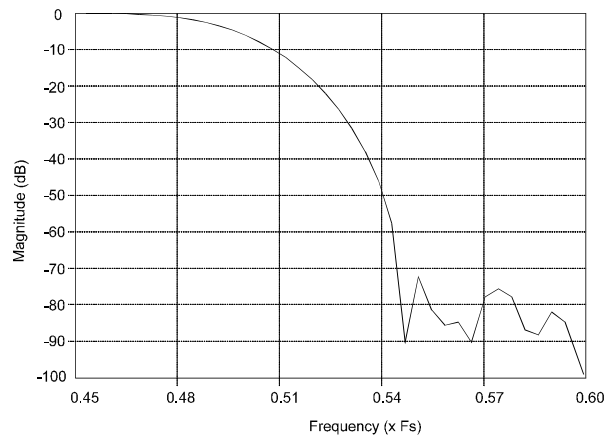


Figure 10. CS4390 Combined Digital and Analog Filter Stopband Rejection

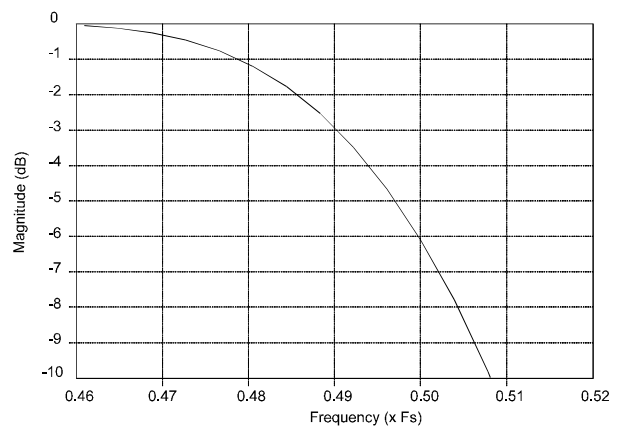


Figure 11. CS4390 Combined Digital and Analog Filter Transition Band

Analog Output and Filtering

The analog output should be operated in a differential mode which allows for the cancellation of common mode errors including noise, distortion and offset voltage. Each output will produce a nominal 2.83 Vpp (1 Vrms) output for a full scale digital input which equates to a 5.66 Vpp (2 Vrms) differential signal as shown in Figure 12.

Figure 13 displays the CS4390 output noise spectrum. The noise beyond the audio band can be further reduced with additional analog filtering. The applications note "Design Notes for a 2-Pole Filter with Differential Input" discusses the second-order Butterworth filter and differential to signal-ended converter which was implemented on the CS4390 evaluation board, CDB4390. The CS4390 filter is a linear phase design and does not include phase or amplitude compensation for an external filter. Therefore, the DAC system phase and amplitude response will be dependent on the external analog circuitry.

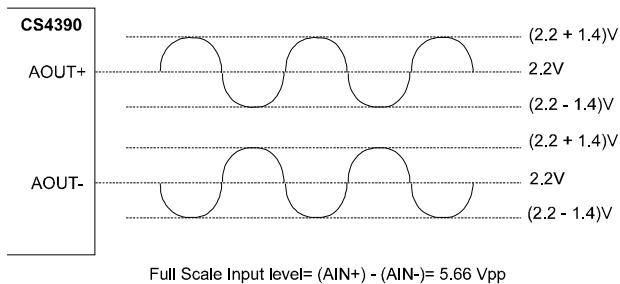


Figure 12. Full Scale Input Voltage

Grounding and Power Supply Decoupling

As with any high resolution converter, the CS4390 requires careful attention to power supply and grounding arrangements to optimize performance. Figure 1 shows the recommended power arrangements with VA+ connected to a clean +5 volt supply. VD+ should be derived from VA+ through a 2 ohm resistor. VD+ should not be used to power additional digital circuitry. This technique minimizes digital noise and insures proper power supply matching and sequencing. Decoupling capacitors should be located as near to the CS4390 as possible.

The printed circuit board layout should have separate analog and digital regions with individual ground planes. Extensive use of ground plane fill on both the analog and digital sections of the circuit board will yield large reductions in radiated noise effects. An application note "Layout and Design Rules for Data Converters" is printed in the 1994 Audio Data book.

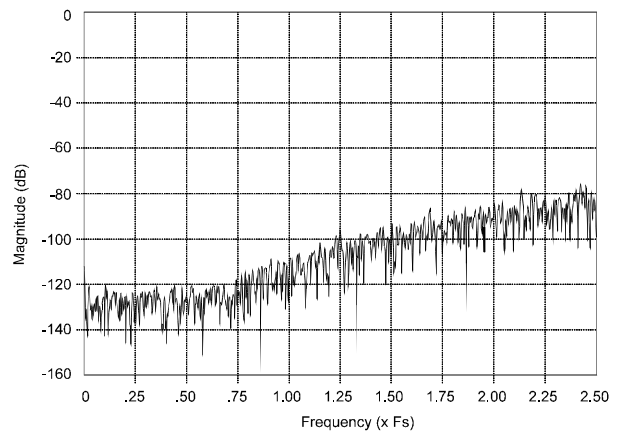
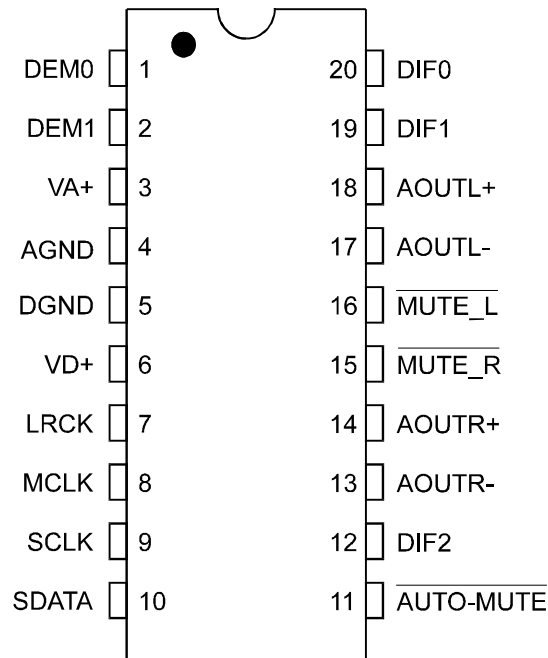


Figure 13. CS4390 Output Noise Spectrum

PIN DESCRIPTIONS**Power Supply Connections****VA+ - Positive Analog Power, PIN 3.**

Positive analog supply. Nominally +5 volts.

VD+ - Positive Digital Power, PIN 6.

Positive supply for the digital section. Nominally +5 volts.

AGND - Analog Ground, PIN 4.

Analog ground reference.

DGND - Digital Ground, PIN 5.

Digital ground for the digital section.

Analog Outputs**AOUTR+,AOUTR- - Differential Right Channel Analog Outputs, PIN 14, PIN 13.**

Analog output connections for the Right channel differential outputs. Nominally 2 Vrms (differential) for full-scale digital input signal.

AOUTL+,AOUTL- - Differential Left Channel Analog Outputs, PIN 18, PIN 17.

Analog output connections for the Left channel differential outputs. Nominally 2 Vrms (differential) for full-scale digital input signal.

Digital Inputs

MCLK - Clock Input, PIN 8.

The frequency must be either 256×, 384× or 512× the input sample rate (Fs).

LRCK - Left/Right Clock, PIN 7.

This input determines which channel is currently being input on the Serial Data Input pin, SDATA. The format of LRCK is controlled by DIF0, DIF1 and DIF2.

SCLK - Serial Bit Input Clock, PIN 9.

Clocks the individual bits of the serial data in from the SDATA pin. The edge used to latch SDATA is controlled by DIF0, DIF1 and DIF2.

SDATA - Serial Data Input, PIN 10.

Two's complement MSB-first serial data of either 16, 18, 20, or 24 bits is input on this pin. The data is clocked into the CS4390 via the SCLK clock and the channel is determined by the LRCK clock. The format for the previous two clocks is determined by the Digital Input Format pins, DIF0, DIF1 and DIF2.

DIF0, DIF1, DIF2 - Digital Input Format, PINS 20, 19, 12

These three pins select one of seven formats for the incoming serial data stream. These pins set the format of the SCLK and LRCK clocks with respect to SDATA. The formats are listed in Table 2. NOTE: Format 1 is not compatible with the CS4329.

DEM0, DEM1 - De-Emphasis Select, PINS 1, 2.

Controls the activation of the standard 50/15us de-emphasis filter for either 32, 44.1 or 48 kHz sample rates.

$\overline{\text{AUTO-MUTE}}$ - Automatic Mute on Zero-Data, PIN 11.

When $\overline{\text{Auto-Mute}}$ is low the analog outputs are muted following 8192 consecutive LRCK cycles of all 0's or 1's data. Mute is canceled with the return of non-zero input data.

$\overline{\text{MUTE_R}}$, $\overline{\text{MUTE_L}}$ Mute, PINS 15, 16.

$\overline{\text{MUTE_L}}$ low activates a muting function for the Left channel. $\overline{\text{MUTE_R}}$ low activates a muting function for the Right channel.

PARAMETER DEFINITIONS

Dynamic Range

The ratio of the full scale rms value of the signal to the rms sum of all other spectral components over the specified bandwidth. Dynamic range is a signal-to-noise measurement over the specified bandwidth made with a -60 dBFS signal. 60dB is then added to the resulting measurement to refer the measurement to full scale. This technique ensures that the distortion components are below the noise level and do not effect the measurement. This measurement technique has been accepted by the Audio Engineering Society, AES17-1991, and the Electronic Industries Association of Japan, EIAJ CP-307.

Total Harmonic Distortion + Noise

The ratio of the rms value of the signal to the rms sum of all other spectral components over the specified bandwidth (typically 10Hz to 20kHz), including distortion components. Expressed in decibels.

Idle Channel Noise / Signal-to-Noise-Ratio

The ratio of the rms analog output level with 1kHz full scale digital input to the rms analog output level with all zeros into the digital input. Measured A-weighted over a 10Hz to 20kHz bandwidth. Units in decibels. This specification has been standardized by the Audio Engineering Society, AES17-1991, and referred to as Idle Channel Noise. This specification has also been standardized by the Electronic Industries Association of Japan, EIAJ CP-307, and referred to as Signal-to-Noise-Ratio.

Interchannel Isolation

A measure of crosstalk between the left and right channels. Measured for each channel at the converter's output with all zeros to the input under test and a full-scale signal applied to the other channel. Units in decibels.

Frequency Response

A measure of the amplitude response variation from 10Hz to 20kHz relative to the amplitude response at 1kHz. Units in decibels.

De-Emphasis Error

A measure of the difference between the ideal de-emphasis filter and the actual de-emphasis filter response. Measured from 10Hz to 20kHz. Units in decibels.

Interchannel Gain Mismatch

The gain difference between left and right channels. Units in decibels.

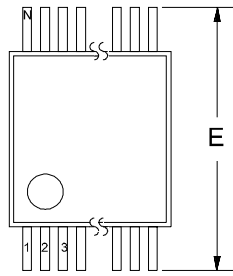
Gain Error

The deviation from the nominal full scale analog output for a full scale digital input.

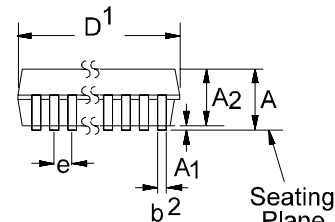
Gain Drift

The change in gain value with temperature. Units in ppm/°C.

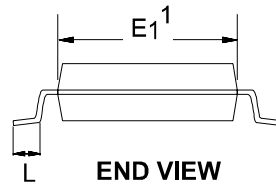
PACKAGE DIMENSIONS



TOP VIEW



SIDE VIEW



END VIEW

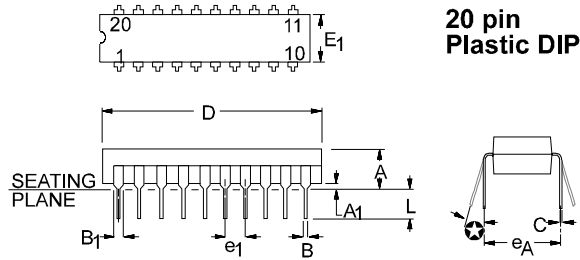
SSOP Package Dimensions

Notes:

- "D" and "E1" are reference datums and do not include mold flash or protrusions, but do include mold mismatch and are measured at the parting line, mold flash or protrusions shall not exceed 0.20mm per side.
- Dimension b does not include dambar protrusion/intrusion. Allowable dambar protrusion shall be 0.13mm total in excess of b dimension at maximum material condition. Dambar intrusion shall not reduce dimension b by more than 0.07mm at least material condition.
- These dimensions apply to the flat section of the lead between 0.10 and 0.25mm from lead tips.

DIM	MILLIMETERS			INCHES			Note
	MIN	NOM	MAX	MIN	NOM	MAX	
A	-	-	2.13	-	-	0.084	
A1	0.05	0.15	0.25	0.002	0.006	0.010	
A2	1.62	1.75	1.88	0.064	0.070	0.074	
b	0.22	0.30	0.38	0.009	0.012	0.015	2,3
D	see other table			see other table			1
E	7.40	7.80	8.20	0.291	0.307	0.323	
E1	5.00	5.30	5.60	0.197	0.209	0.220	1
e	0.61	0.65	0.69	0.024	0.026	0.027	
L	0.63	0.90	1.03	0.025	0.035	0.040	
N	see other table			see other table			
∞	0°	4°	8°	0°	4°	8°	

N	D						Note
	MILLIMETERS			INCHES			
	MIN	NOM	MAX	MIN	NOM	MAX	
20	6.90	7.20	7.50	0.272	0.283	0.295	1
28	9.90	10.20	10.50	0.390	0.402	0.413	1



DIM	MILLIMETERS			INCHES		
	MIN	NOM	MAX	MIN	NOM	MAX
A	3.94	-	4.57	0.155	-	0.180
A ₁	0.51	0.80	1.02	0.020	0.030	0.040
B	0.38	0.46	0.56	0.015	0.018	0.022
B ₁	1.27	1.52	1.78	0.050	0.060	0.070
C	0.20	0.25	0.38	0.008	0.010	0.015
D	24.38	25.40	26.42	0.960	1.000	1.040
E ₁	6.10	6.35	6.60	0.240	0.250	0.260
e ₁	2.41	2.54	2.67	0.095	0.100	0.105
e _A	7.62	7.92	8.25	0.300	0.312	0.325
L	3.18	3.30	3.81	0.125	0.130	0.150
α	0°	-	15°	0°	-	15°

NOTES:

1. POSITIONAL TOLERANCE OF LEADS SHALL BE WITHIN 0.25mm (0.010") AT MAXIMUM MATERIAL CONDITION, IN RELATION TO SEATING PLANE AND EACH OTHER.
2. DIMENSION e_A TO CENTER OF LEADS WHEN FORMED PARALLEL.
3. DIMENSION E₁ DOES NOT INCLUDE MOLD FLASH.

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